

Graph Neural Networks to evaluate KPIs

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Introduction

- Digital Twin → virtual representation of a real object. Explore configurations to analyze impact. Typical use cases:
 - Engineering of physical objects \rightarrow test any design reducing development costs.
 - \circ **Operations management** \rightarrow networks, logistics, maintenance, business process optimization...
- Use case on communication networks, 5G and B5G:
 - Complex, strict Service Level Agreement (SLA) services e.g., AR, V2X, IoT.
 - Key Performance Indicators (KPIs) \rightarrow delay, jitter, loss, throughput in real time.
 - Network Slicing management (admission control, orchestration) with low response times.





Tools to build a Digital Twin Network

Solutions for predicting network properties:

	Advantages	Disadvantages			
Analytical modeling	Fast predictions	Non-realistic and static network properties, poor predictions			
Packet simulators	High precision	High computational complexity and execution time			
Traditional AI/ML models	Easy model update/retrain, fast KPIs prediction	Not designed for graph data, poor predictions			
Graph Neural Networks (GNNs)	ML models optimized for graphs. Fast and reliable KPIs prediction	Complex to develop, generalization problems with different size networks			



How do GNNs work? (I)

Intuition: Nodes **aggregate** information from their **neighbors** using neural networks.





How do GNNs work? (II)

Intuition: Nodes aggregate information from their neighbors using neural networks.





How do GNNs work? (III)

GNN Layer = Message + Aggregation





How do GNNs work? (IV)

Problem! Oversmoothing: in the 3-layer GNN all node values converge to the same value.



How do GNNs work? (V)

BCDS Universitat de Girona

Connect GNN layers:

- Stack layers sequentially.
- Ways of adding skip connections to improve generalization.







How do GNNs work? (VI)



Techniques to adapt the data to a GNN, helping with generalization:

- Graph feature augmentation: new features from the existing ones.
- Graph **structure manipulation**: new nodes or edges, or completely rebuilt graph based on original data.

GNN training: supervised/unsupervised. GNN predictions: **node/edge/graph** level.



GNN use case



Performance prediction in larger unseen networks

- **GNNs generalization problem** \rightarrow GNN complexity and errors increase with network size.
- This work started with our participation in the AI/ML in 5G ITU Graph Neural Networking Challenge 2021. Creating a Scalable Network Digital Twin. Further work after the competition was realized.
- Joint work with the University of Antwerp, resulting in GAIN team \rightarrow Girona & Antwerp Intelligence for Networking.
- Conference publication: Farreras, M., Soto, P., Camelo, M., Fàbrega, L., Vilà, P. (2022). Predicting network performance using GNNs: generalization to larger unseen networks. <u>https://doi.org/10.1109/NOMS54207.2022.9789766</u>
- Journal publication: in preparation







Problem description

- GNN baseline, called RouteNet, provided by the challenge organizers (Barcelona Neural Networking Center, UPC).
- RouteNet predicts per-path mean delay, jitter, loss; here the focus is on per-path mean delay.
- Efficient to generalize with topologies, routings and traffic not seen before.
- But poor generalization when graph size and features are bigger than training samples.
- Link and path features available.
- The prediction error was measured using the Mean Average Percentage Error (MAPE).
- RouteNet baseline achieved 187% MAPE.
- Dataset: small networks for training and larger networks for validation/testing (higher number of nodes, higher link capacities, longer paths)





Our improvements

• Use **link features** instead of path features, postprocessing of the GNN result:



- Min-max normalization of predictor features: analysis of train, validation and test datasets.
- **Feature selection** based on correlation tests.
- **Feature augmentation**: creation of a feature called offered traffic intensity of a link. Sum of flows traversing a link in a [0..1] range:



• **Hyper-parameter optimization**: less training time and GPU/power consumption.

Results



TEST DATASET MAPE (%) RESULTS AND PERFORMANCE FOR BASELINE AND EACH GAIN SOLUTION

	Full testing dataset	S_1	S ₁ 50 nodes	S ₁ 300 nodes	S_2	S2 50 nodes	S2 300 nodes	S_3	S ₃ 50 nodes	S ₃ 300 nodes	Train time
Baseline	187.28	79.145	68.481	92.979	253.075	68.481	345.135	247.217	44.669	368.019	12h 15m
GAIN 1	44.73	13.074	11.705	13.108	54.318	16.214	42.374	67.44	70.994	90.739	9h 45m
GAIN 2	28.739	11.719	11.026	11.864	35.067	17.092	39.773	31.754	17.581	31.353	9h 48m
GAIN 3	18.471	9.436	6.893	12.468	26.897	22.106	30.067	18.143	12.569	21.862	9h 40m
GAIN 4	2.612	2.652	1.539	3.687	2.492	1.386	2.567	2.584	1.607	2.363	3h 25m
GAIN 5	1.838	1.407	1.111	1.808	1.929	1.573	1.535	1.756	1.388	1.462	2h 20m

GAIN 1: Inferring per-path delay from predicted queue occupancy

- GAIN 2: Normalization of predictor features
- GAIN 3: Feature selection
- GAIN 4: Feature augmentation: Offered Traffic Intensity

GAIN 5: Hyper-parameters optimization

Setting 1 (S_1): Longer paths. Setting 2 (S_2): Increased link capacity. Setting 3 (S_3): Both properties mixed.



Future work

- Improve the previous work to achieve greater performance and evaluate the implications.
- Closed-loop control context for SDN-NFV.
- Investigate other GNN architectures: different input graphs and newer GNN implementations.
- Generation of network slicing datasets.
- Adaptation of a GNN model to orchestrate a network slicing infrastructure.



Any questions?